

Matrix Completion from a Few Entries

Raghunandan Keshavan, Andrea Montanari and Sewoong Oh

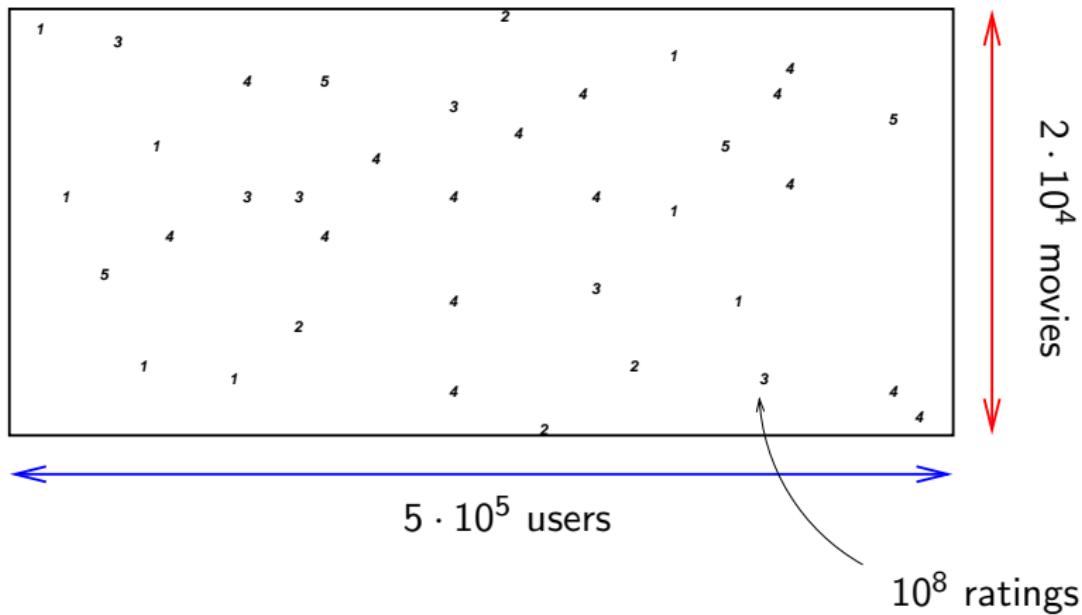
Stanford University

Physics of Algorithms
Santa Fe - Aug 31, 2009

Motivating Example : Recommender System

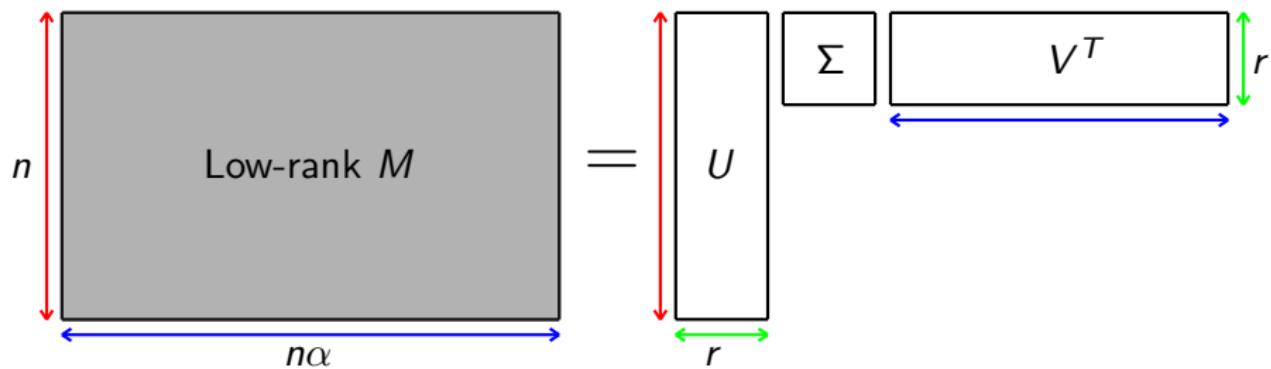
- Netflix Challenge

$M =$



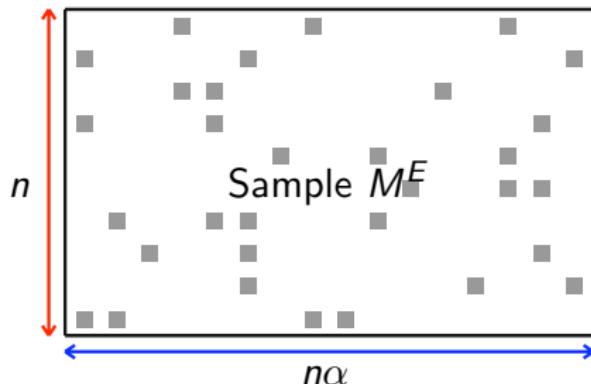
The Model

Matrix Completion Problem



1. Low-rank matrix $M = U\Sigma V^T$.
 $U^T U = n, \quad V^T V = n\alpha, \quad \Sigma = \text{diag}(\Sigma_1, \Sigma_2, \dots, \Sigma_r)$
2. Uniformly random sample $E \subset [n] \times [n\alpha]$ given its size $|E|$.
 $[k] = \{1, 2, \dots, k\}$

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Matrix Completion Problems

For any estimation \hat{M} , let $\text{RMSE} = \left(\frac{1}{\sqrt{mn}} \|M - \hat{M}\|_F \right)$

$$\|A\|_F^2 = \sum_{ij} A_{ij}^2$$

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Q1. How many samples do we need to get $\text{RMSE} \leq \delta$?

$$(1 + \alpha)mn \lesssim |E| = O(nr)$$

Q2. How many samples do we need to recover M exactly?

$$n \log n \lesssim |E| = O(n \log n)$$

Q3. What if the samples are corrupted by noise?

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Pathological Example

$$M = e_1 e_1^T$$

$$\begin{array}{c} \uparrow \\ n \\ \downarrow \end{array} \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix}$$

$$\mathbb{P}(\text{observing } M_{11}) = \frac{|E|}{n^2}$$

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Incoherence Property

M is (μ_0, μ_1) -incoherent if

$$A1. \quad M_{\max} \leq \mu_0 \Sigma_1 \sqrt{r}; ,$$

$$A2. \quad \sum_{a=1}^r U_{ia}^2 \leq \mu_1 r, \quad \sum_{a=1}^r V_{ja}^2 \leq \mu_1 r.$$

[Candés, Recht 2008 [1]]

Previous Work

Theorem (Candés, Recht 2008 [1])

Let M be an $n \times n\alpha$ matrix of rank r satisfying (μ_0, μ_1) -incoherence condition. If

$$|E| \geq C(\alpha, \mu_0, \mu_1) r n^{6/5} \log n ,$$

then w.h.p. SEMIDEFINITE PROGRAMMING reconstructs M exactly.

Main Contributions

Questions	Main Results
1. RMSE	$\leq C(\alpha) \left(\frac{nr}{ E } \right)^{\frac{1}{2}}$
2. Exact Reconstruction	$ E = O(n \log n)$
3. Noisy Reconstruction $(N = M + Z)$	$ E = O(n \log n)$ $\frac{1}{\sqrt{mn}} \ M - \hat{M}\ _F \leq C \frac{n\sqrt{\alpha r}}{ E } \ Z^E\ _2$
4. Complexity?	$O(E r \log n)$

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The Algorithm and Main Theorems

Naïve Approach

$$M_{ij}^E = \begin{cases} M_{ij} & \text{if } (i,j) \in E, \\ 0 & \text{otherwise.} \end{cases}$$

$$M^E = \sum_{k=1}^n x_k \sigma_k y_k^T$$

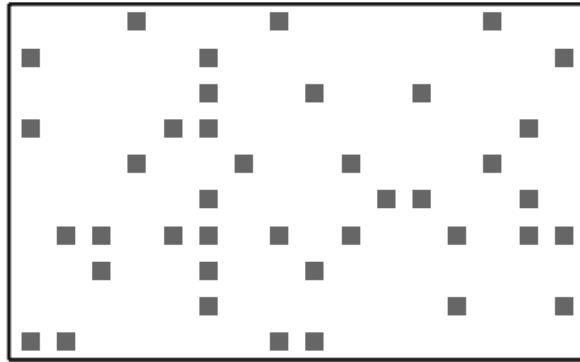
Rank- r projection :

$$\mathcal{P}_r(M^E) \equiv \frac{n^2 \alpha}{|E|} \sum_{k=1}^r x_k \sigma_k y_k^T$$

Naïve Approach Fails

- Define : $\deg(\text{row}_i) \equiv \# \text{ of samples in row } i$.
- For $|E| = O(n)$, spurious singular values of $\Omega(\sqrt{\log n / (\log \log n)})$.
- Solution : Trimming

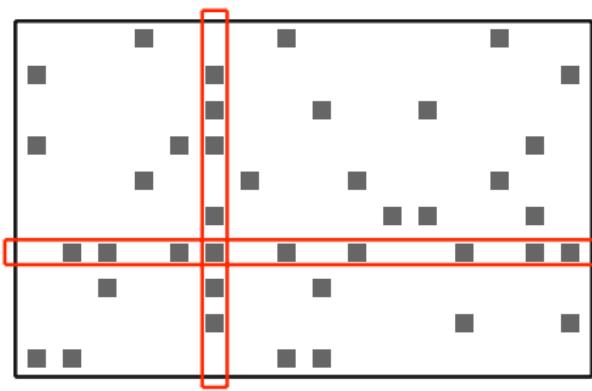
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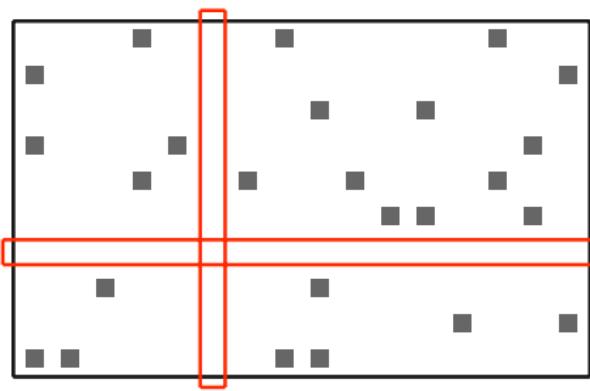
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The Algorithm

OPTSPACE

Input : sample positions E , sample values M^E , rank r

Output : estimation \hat{M}

- 1: Trim M^E , and let \tilde{M}^E be the output;
 - 2: Compute rank- r projection $\mathcal{P}_r(\tilde{M}^E) = X_0 S_0 Y_0^T$;
 - 3:
-

Main Result

Theorem (Keshavan, Montanari, Oh, 2009 [2])

Let M be an $n \times n\alpha$ matrix of rank- r bounded by M_{\max} . Then, w.h.p,

$$\frac{1}{nM_{\max}} \|M - \mathcal{P}_r(\tilde{M}^E)\|_F = \text{RMSE} \leq C(\alpha) \sqrt{\frac{nr}{|E|}},$$

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 - 3: Minimize $F(X, Y)$ by gradient descent starting at (X_0, Y_0) .
-

$$F(X, Y) = \min_{S \in \mathbb{R}^{r \times r}} \sum_{(i,j) \in E} \left(M_{ij} - (XSY^T)_{ij} \right)^2$$

Main Result

Theorem (Keshavan, Montanari, Oh, 2009 [2])

Assume $r = O(1)$, and let M be an $n \times n\alpha$ matrix satisfying (μ_0, μ_1) -incoherence with $\sigma_1(M)/\sigma_r(M) = O(1)$. If

$$|E| \geq C'n \log n ,$$

then OPTSPACE returns, w.h.p., the matrix M .

Comparison

Theorem (Candés, Tao, 2009 [3])

Assume a strongly incoherent matrix M .

If $|E| \geq C r n (\log n)^6$ then

SEMIDEFINITE PROGRAMMING returns, w.h.p., the matrix M .

Corrupted Observations

- $N = M + Z$ for any $n \times n\alpha$ matrix Z
- N^E (defined similar to M^E) input to OPTSPACE

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Theorem (Keshavan, Montanari, Oh, 2009 [4])

Let $N = M + Z$ with M as above and Z any $n \times n\alpha$ matrix. If $|E| \geq C'n \log n$, then OPTSPACE with input N^E returns \hat{M} such that w.h.p.,

$$\frac{1}{\sqrt{mn}} \|M - \hat{M}\|_F \leq C \frac{n\sqrt{\alpha r}}{|E|} \|Z^E\|_2$$

provided that the right hand side is smaller than Σ_r .

$$\|A\|_2 = \sup_{v \neq 0} \left(\frac{\|Av\|}{\|v\|} \right)$$

Corrupted Observations

- Z_{ij} are independent, $\mathbb{E}\{Z_{ij}\} = 0$ and $P\{|Z_{ij}| \geq x\} \leq Ce^{-\frac{x^2}{2\sigma^2}}$

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Theorem (Keshavan, Montanari, Oh, 2009 [4])

If Z is a random matrix with entries drawn as above, then

$$\|\tilde{Z}^E\|_2 \leq C\sigma \left(\frac{\sqrt{\alpha}|E| \log |E|}{n} \right)^{\frac{1}{2}}$$

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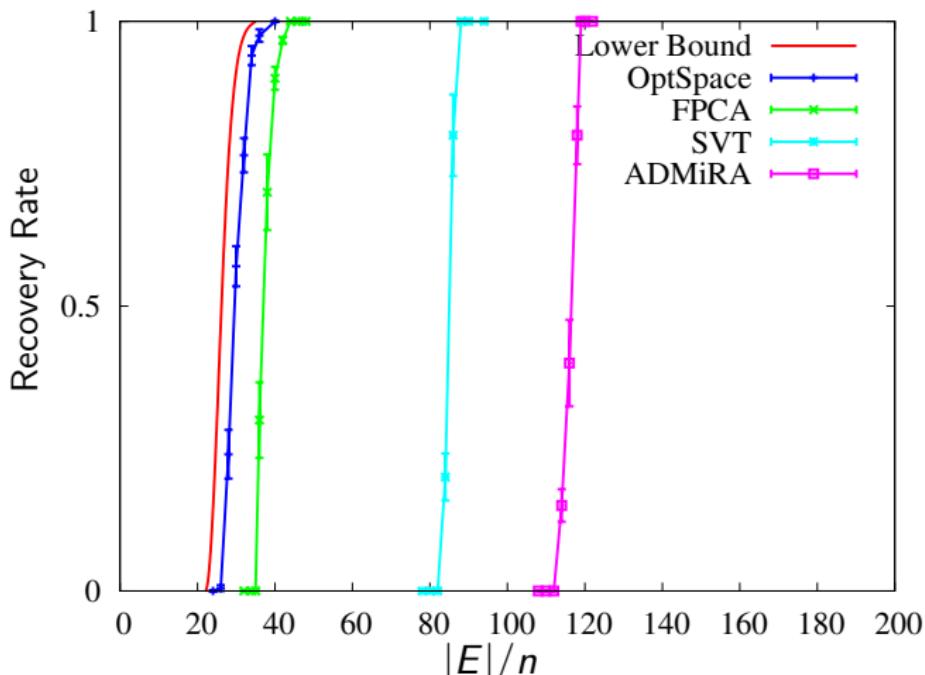
Corollary

Let $N = M + Z$, with Z distributed as above. Then, OPTSPACE with input N^E returns \hat{M} such that

$$\frac{1}{\sqrt{mn}} \|M - \hat{M}\|_F \leq C\alpha\sigma \left(\frac{nr}{|E|} \right)^{\frac{1}{2}} \sqrt{\log |E|}$$

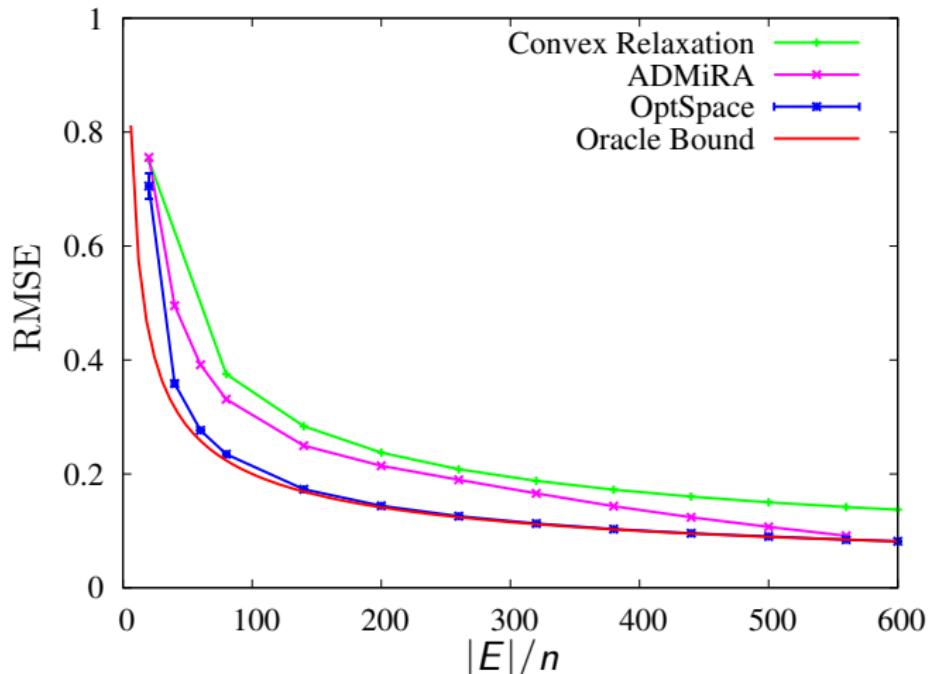
Simulation Results

- $M = UV^T$, $U_{ij} \sim N(0, 1)$, $V_{ij} \sim N(0, 1)$
- $r = 10$, $\alpha = 1$, $n = 1000$
- M is recovered if $\|M - \hat{M}\|_F / \|M\|_F < 10^{-4}$



Simulation Results

- $U_{ij} \sim N(0, \sigma^2 = 20/\sqrt{n})$ [5]
- $Z_{ij} \sim N(0, 1)$
- $r = 2, \alpha = 1, n = 600$



Conclusion

Main Results

- ① RMSE $\leq \delta$: $|E| = O(nr)$
- ② Exact : $|E| = O(n \log n)$
- ③ Noisy : $\leq C \frac{n\sqrt{\alpha r}}{|E|} \|Z^E\|_2$
- ④ Complexity : $O(|E|r \log n)$

What's left?

- ① Prior knowledge of rank?
RANKESTIMATION is exact w.h.p for $|E| = O(n)$
- ② $r = \Theta(n^\beta)$?
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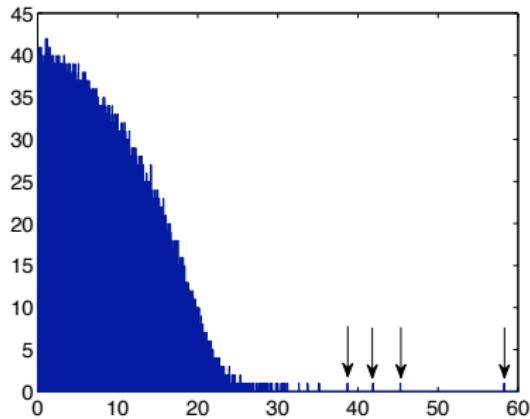
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Untrimmed SVD



Trimmed SVD

